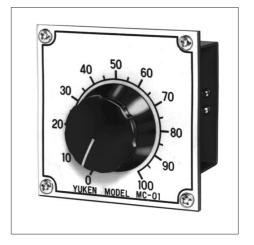
## Setting Adjusters

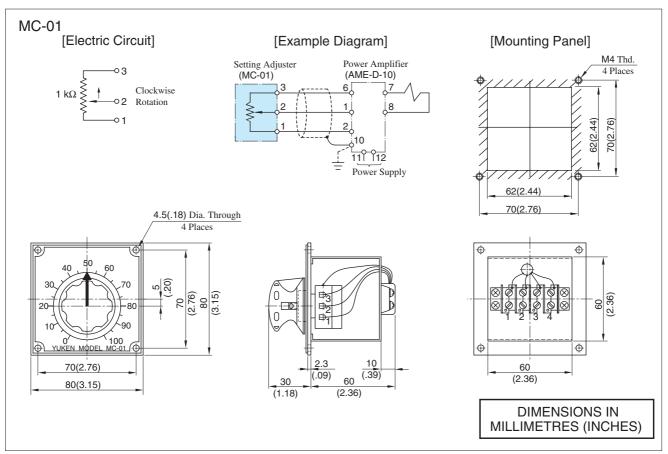
The setting adjuster supplies the command signal voltage to the power amplifier. Since the setting adjuster is closely related to actual machine operating procedure, the user generally provides this device. Yuken makes the following standard setting adjusters for general use and designs and manufactures special setting adjusters to order.

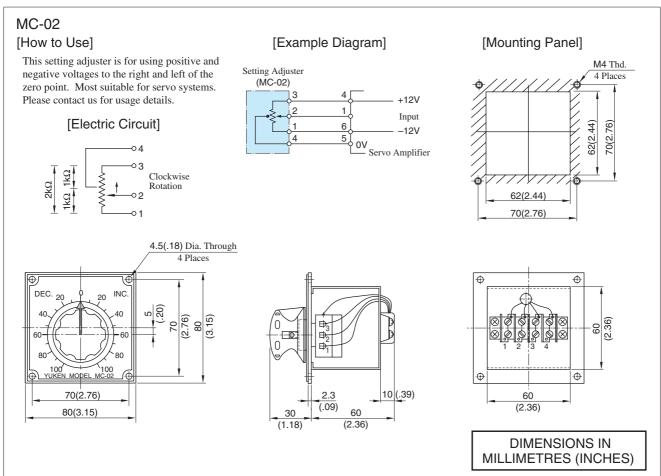


Туре	Model Number	Function
Manually Operated	MC-01	This is the simplest setting adjuster, consisting of a trimmer (1 k $\Omega$ ) and a dial.
Setting Adjuster	MC-02	Consisting of a centre-tapped trimmer (1 k $\Omega$ - 1 k $\Omega$ ) and a dial, this setting adjuster is ideal for a servo system.
6-point Setting Adjuster	AMC-V6-S-*-10	Six trimmers are incorporated, so it is possible to set six points.
Multifunction Slope Controller	AMC-T-20	This multifunction slope controller generates any desired two-channel analog voltage pattern outputs. It can also be used with slope-proportional and time-proportional systems.
Slope Controller	AMN-T-10	Slope and output can be set optionally 4-bit signal.

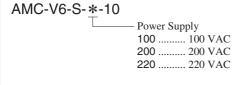


## Manually Operated Setting Adjuster

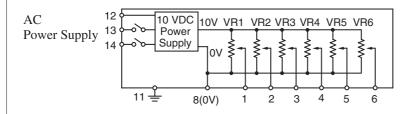




## 6-Point Setting Adjuster



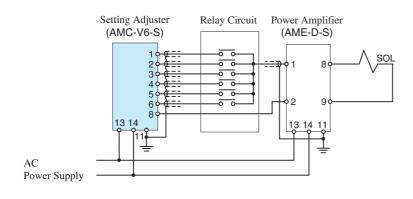
## [Electric Circuit]

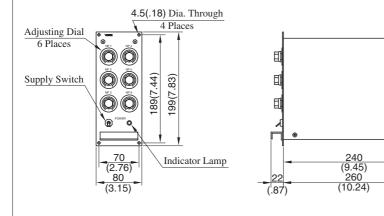


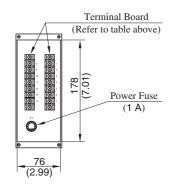
#### Detail of Terminal Board

Terminal Number	Name	
1	1 OUT (VR1)	
2	2 OUT (VR2)	
3	3 OUT (VR3)	
4	4 OUT (VR4)	
5	5 OUT (VR5)	
6	6 OUT (VR6)	
7		
8	0V	COM
9		
10		
11	Ground	G
12	Power Supply	
13	85 – 265 VAC	
14		

## [Example Diagram]







DIMENSIONS IN MILLIMETRES (INCHES)



## Multifunction Slope Controllers

This controller can generate any desired two-channel analog voltage pattern outputs and can be used with slope-constant and time-constant systems. Although two-channel outputs can be used independently, this controller can also be used as a setting adjuster for the EH Series variable piston pumps.

## Model Number Designation

AMC	-т	-20
Series Number	Type of Function	Design Number
AMC: Setting Adjuster	T : Acceleration/deceleration signal type (Slope Controller)	20



### Specifications

Model No. Description	AMC-T-20	
Number of Output Channels	2 channels (A, B)	
Maximum Output Range	$0 - +5 \text{ V}^*$ , $0 - \pm 5 \text{ V}$ , $0 - +10 \text{ V}$ , $0 - \pm 10 \text{ V}$ (The settings are DIP switch selectable)	
Two Categories of Slopes	Slope-constant *  With a level change, the slope will not change (but arrival time changes.)  Time-constant  With a level change, the time will not change (but the slope changes.)	
Acceleration/Deceleration Signal Type	4 Types Polygonal Line Signal * : 1 Type (to be selected Curve Compensation Signal : 3 Types (by DIP switch)	
Max. Slope Time	5 s*, 20 s, 50 s, 100 s (The settings are DIP switch selectable)	
Setting Resolution	The level and slope settings are variable in 0.1% units from 0 to ±99.9%	
Control Mode Number of Preselected Patterns	Mode 1, 4-bit binary code input, 15 patterns Mode 2, 6-bit binary code input, 63 patterns Mode 3, Timer control, 9 patterns (4 variations)	
Stop Mode (Applicable Only for Control Mode 1	ON: The stop mode is to retain the state of controller output at the instant an external input signal is interrupted. When the external signal is input again, the operation is resumed from the retained state. OFF*: When external input signal is interrupted, function goes back to the initial setting (Pattern No.0).	
Control Input Signal	Current input type, 10 mA /bit max. Usable as a voltage input type (voltage range: 8 to 48V DC) Photocoupler insulation input	
Control Output Signal	Output from transister open collector Max. 30V, 50 mA	
Data Save	EEP-ROM (Battery not needed)	
Power Supply	100/200 V AC, 50/60 Hz (85-260 V AC)	
Power Input	10 VA or less	
Ambient Temperature	0-50°C (32-122°F)	
Ambient Humidity	85%RH or less (Bedewing must be avoided)	
Approx. Mass	1 kg (2.2 lbs.)	

Note: ★ Indicates preset conditions.

#### Instructions

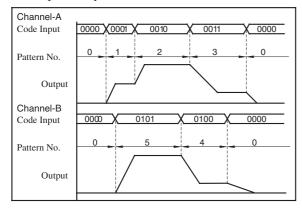
• Since this controller incorporates a micro computer, do subject it to undue electrical noise.

#### Control Modes

One among the following three types of control modes can be chosen by changing DIP swicth.

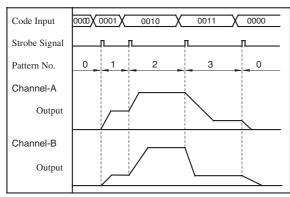
#### Control Mode 1

Channels A and B generate optional slopes independently each other.



#### Control Mode 2

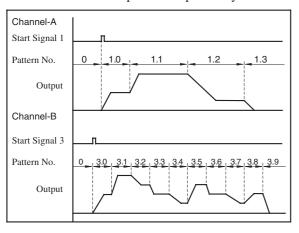
A slope is generated by a strobe signal (signal for change to next signal). Channels A and B operate synchronously.



#### Control Mode 3

The internal timer is activated by a start signal, causing the slopes to be generated successively in memory.

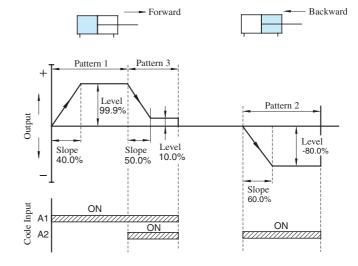
Channels A and B operate independently.



## Setting Example

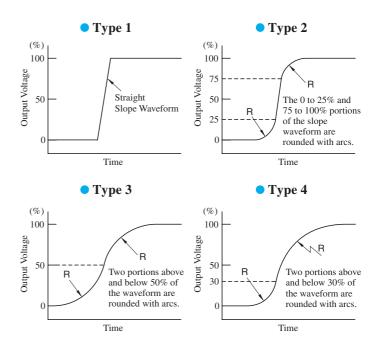
#### Ocontrol Mode 1 Channel - A

	Code Input		Pattern	Pattern Setting %		Remarks	
A8	A4	A2	A1	No.	Level	Slope	Remarks
OFF	OFF	OFF	OFF	0	0	0	Stop
OFF	OFF	OFF	(ON)	1	99.9	40.0	Cylinder forward acceleration
OFF	OFF	(ON)	OFF	2	-80.0	60.0	Cylinder backward acceleration
OFF	OFF	(ON)	(ON)	3	10.0	50.0	Cylinder forward deceleration
$\sim$							
(ON)	(ON)	(ON)	(ON)	15	10.0	10.0	

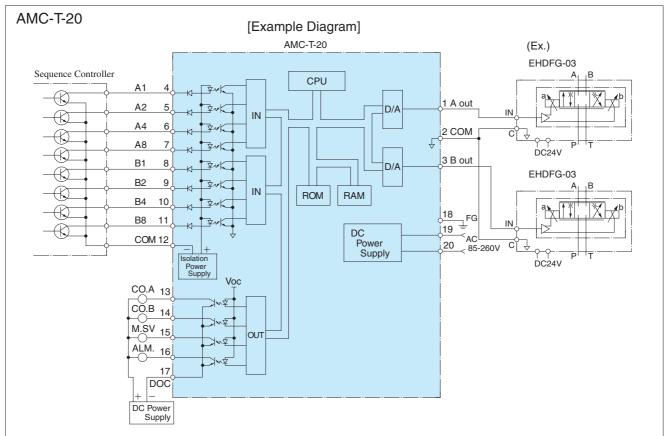


#### Slope Type

One among the follwing four types can be chosen by changing DIP switch.

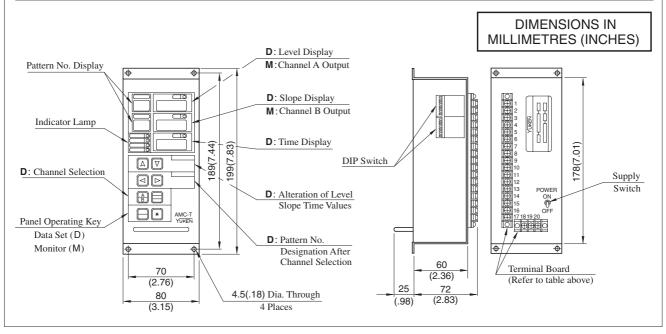






#### Detail of Terminal Board

Terminal Number	Name	Terminal Number	Name	
1	Channel A Output A out	11	Code Input	B8
2	Common COM	12	Code Input Common	DCOM
3	Channel B Output B out	13	Coincidental Output Signal with "A"	CO.A
4	Code Input A1	14	Coincidental Output Signal with "B"	CO.B
5	Code Input A2	15	Data Save Signal	M.SV
6	Code Input A4	16	Alarm Signal Output	ALM.
7	Code Input A8	17	Output Common	DOC
8	Code Input B1	18	Frame Ground	FG
9	Code Input B2	19	Dower Cumply	AC
10	Code Input B4	20	Power Supply	AC



## ■ Interchangeability between Current and New Design

#### Specifications

Specifications unchanged unless specified below.

Model No. Description	New : AMC-T-20	Current : AMC-T-10
Control Output Signal	Output from transister open collector Max. 30 V, 50 mA	Output from transister open collector Max. 30 V, 10 mA
Slope Types	4 Types Polygonal Line Signal : 1 Type (to be selected by DIP switch)	1 Type : Polygonal Line Signal
Stop Mode (Applicable only for Control Mode 1)	ON, OFF	
Data Save	EEP-ROM Battery not needed	Battery Required
Approx. Mass	1 kg (2.2 lbs.)	1.8 kg (4.0 lbs.)

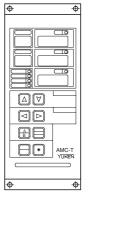
#### Terminal

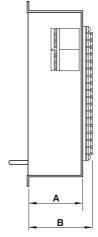
The following are differences between current and new.

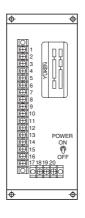
Terminal	Na	Remarks		
Number	New: Design 20	Current : Design 10	Remarks	
13	Coincidental Output Signal with "A" "CO.A"	Coincidental Output Signal with "A" "DO1"	Abbreviation of the terminals are changed,	
14	Coincidental Output Signal with "B" "CO.B"	Coincidental Output Signal with "B" "DO2"	though functionally the same.	
15	Data Save Signal "M.SV"		Added new functions.	
16	Alarm Signal Output "ALM."		Added new functions.	

## Interchangeability in Installation

There is an interchangeability in installation, although depths (dimensions "A" and "B") are different.







Model	Numbers	mm (Inches)		
Model	Numbers	Α	В	
Current	AMC-T-10	185 (7.28)	200 (7.87)	
New	AMC-T-20	60 (2.36)	72 (2.83)	

## Slope Controllers

This slope controller is considerably smaller and lighter compared to conventional slope controllers.

4-bit switching signals allow the pattern output of given levels and acceleration/deceleration times. One-touch disconnection is supported. The mass and the volume have been reduced to one-fifth and one-fourth, respectively.

## Model Number Designation

AMN	-Т	-10
Series Number	Type of Function	Design Number
AMN	T: Slope Controller	10



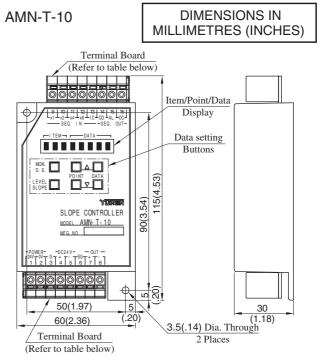
#### Specifications

Model Numbers Description	AMN-T-10
Number of Output Channels	1 channel
Maximum Output Range	0 - +5 V (Factory Preset) 0 - +10 V ±5 V ±10 V
Maximum Slope Time	<ul> <li>Slope-constant type: *1         <ul> <li>1-9999 s/Max. Output signal</li> <li>(Factory Setting, 5 s)</li> </ul> </li> <li>Time-constant type:*2 1–9999 s         <ul> <li>(Can be set in 1 second increments)</li> </ul> </li> </ul>
Acceleration/Deceleration★3 Signal Type	Polygonal Line Signal: 1 Type (Factory Setting) Curve Compensation Signal: 3 Type
Setting Resolution	The level and slope setting are variable in 0.1 % units from 0 to ±99.9%
Number of Preselected Patterns	4-bit binary code input 15 patterns
Sequence Input	Input Current: 10 mA/24 V Voltage Range: 10 – 28 V
Sequence Output	Load Current: Max. 50 mA Supply Voltage: Max. 32 V
Power Supply Voltage	24 VDC (20 – 30 VDC)
Power Input	3 W
Ambient Temperature	0 – 50 °C (32 – 122 °F)
Ambient Humidity	90 % RH or less
Approx. Mass	0.2 kg (.44 lbs)

- ★1. A fixed slope means that the slope endpoint time changes while the slope gradient remains unchanged when the level is changed.
- ★2. A fixed time means that the slope endpoint time remains unchanged when the level is changed.
- ★3. The same slope types as those for the multifunction slope controller are supported. See page 789 for details.

#### Instructions

 Since this controller incorporates a micro computer, do subject it to undue electrical noise.



#### Detail of Terminal Board

Terminal Number	Name	Terminal Number	Name
1	Power Supply +24V	9	Sequence Input ×1
2	Power Supply 0V	10	Sequence Input ×2
3	Frame Ground G	11	Sequence Input ×4
4	Internal Power Supply +24V	12	Sequence Input ×8
5	Internal Power Supply OV	13	Sequence Input IN COM
6	Signal Ground SG	14	Sequence Output COL N.
7	Output Signal +	15	Sequence Output ALARM
8	Output Signal -	16	Sequence Output OUT COM

# [Example Diagram]

